

Study of Some Improved Ratio Type Estimators Using Information on Auxiliary Attributes Under Second Order Approximation

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Abstract

Chakrabarty (1979), Khoshnevisan et al. (2007), Sahai and Ray (1980), Solanki et al. (2012) suggested some estimators to estimate unknown population mean of the study variable. These authors discussed the estimators along with their first order biases and mean square errors(MSE's). In this paper, we have tried to find out the second order biases and mean square errors of some estimators using information on auxiliary attribute. We have compared the performance of the estimators with the help of a numerical illustration.

Keywords: Simple Random Sampling, population mean, study variable, auxiliary attributes, ratio type estimator, product type estimator, Bias and MSE.

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1. Introduction

In the theory of sample surveys, the use of the auxiliary information can increase the precision or accuracy of an estimator of unknown population parameter of interest when study variable y is highly correlated with the auxiliary variable x . But there may be many practical situations when an auxiliary information is not available directly (it is qualitative in nature), that is, an auxiliary information is available in the form of an attribute. For example:

- (a) The height of a person may depend on the fact that whether the person is male or female.
- (b) The efficiency of a Dog may depend on the particular breed of that Dog.
- (c) The yield of wheat crop produced may depend on a particular variety of wheat, etc.

In these situations by taking the advantage of point bi-serial correlation between the study variable y and the auxiliary attribute ϕ along with the prior knowledge of the population parameter of auxiliary attribute, the estimators of population parameter of interest can be constructed.

Consider a sample of size n drawn by simple random sampling without replacement (SRSWOR) from a population of size N . Let y_i and ϕ_i denote the observation on variable y and x respectively for the i^{th} unit ($i=1,2,3,\dots,N$). We note that $\phi_i=1$, if i^{th} unit possesses attributes ϕ and $\phi_i=0$ otherwise. Let $A = \sum_{i=1}^N \phi_i$, and $a = \sum_{i=1}^n \phi_i$ denote the total number

of units in the population and sample respectively possessing attribute x . Let $P = \frac{A}{N}$ and

$p = \frac{a}{n}$ denote the proportion of units in the population and sample respectively possessing attribute ϕ .

Using the information of the point biserial correlation between the study variable and the auxiliary attribute, Naik and Gupta (1996), Shabbir and Gupta (2006), Ab-Alfatah *et al.* (2010) and Singh *et al.* (2007, 2008) have suggested improved estimators for estimating unknown population mean \bar{Y} . In this paper we have studied properties of some estimators under second order of approximation.

1. Some Estimators in Simple Random Sampling

For estimating the population mean \bar{Y} of Y , adapting Chakrabarty (1979) ratio-type estimator in case of attribute auxiliary variable, we have

$$t_1 = (1 - \alpha)\bar{y} + \alpha\bar{y} \frac{P}{p} \quad (2.1)$$

where $\bar{y} = \frac{1}{n} \sum_{i=1}^n y_i$.

Khoshnevisan *et al.* (2007) ratio-type estimator in case of attribute auxiliary attribute is given by

$$t_2 = \bar{y} \left[\frac{P}{\beta p + (1 - \beta)P} \right]^g \quad (2.2)$$

where g is a constant. For $g=1$, t_2 is same as conventional ratio estimator whereas for $g = -1$, it becomes conventional product type estimator.

Adapting Sahai and Ray (1980) estimator for the situation when information is available in form of auxiliary attribute, we have

$$t_3 = \bar{y} \left[2 - \left\{ \frac{p}{P} \right\}^w \right] \quad (2.3)$$

where w is a constant.

Adapting Solanki et al. (2012) estimator for case of attributes, we get an estimator t_4 as

$$t_4 = \bar{y} \left[2 - \left\{ \left(\frac{p}{P} \right)^\lambda \exp \frac{\delta(p - P)}{(p + P)} \right\} \right] \quad (2.4)$$

where λ is a constant, suitably chosen by minimizing mean square error of the estimator t_4 .

1. Notations used

Let us define,

$$e_0 = \frac{\bar{y} - \bar{Y}}{\bar{Y}} \quad \text{and} \quad e_1 = \frac{p - P}{P},$$

then $E(e_0) = E(e_1) = 0$.

For obtaining the bias and MSE expressions of the estimators, following lemmas will be used:

Lemma 3.1

$$(i) \quad V(e_0) = E\{(e_0)^2\} = \frac{N-n}{N-1} \frac{1}{n} C_{02} = L_1 C_{02}$$

$$(ii) \quad V(e_1) = E\{(e_1)^2\} = \frac{N-n}{N-1} \frac{1}{n} C_{20} = L_1 C_{20}$$

$$(iii) \quad COV(e_0, e_1) = E\{e_0 e_1\} = \frac{N-n}{N-1} \frac{1}{n} C_{11} = L_1 C_{11}$$

Lemma 3.2

$$E\{(e_1^2 e_0)\} = \frac{(N-n)}{(N-1)} \frac{(N-2n)}{(N-2)} \frac{1}{n^2} C_{21} = L_2 C_{21}$$

$$(i) \quad E\{(e_1^3)\} = \frac{(N-n)(N-2n)}{(N-1)(N-2)} \frac{1}{n^2} C_{30} = L_2 C_{30}$$

Lemma 3.3

$$(ii) \quad E(e_1^3 e_0) = L_3 C_{31} + 3L_4 C_{20} C_{11}$$

$$(iii) \quad E\{(e_1^4)\} = \frac{(N-n)(N^2 + N - 6nN + 6n^2)}{(N-1)(N-2)(N-3)} \frac{1}{n^3} C_{30} = L_3 C_{40} + 3L_4 C_{20}^2$$

$$(iv) \quad E(e_1^2 e_0^2) = L_3 C_{40} + 3L_4 C_{20}$$

Where
$$L_3 = \frac{(N-n)(N^2 + N - 6nN + 6n^2)}{(N-1)(N-2)(N-3)} \frac{1}{n^3}$$

$$L_4 = \frac{N(N-n)(N-n-1)(n-1)}{(N-1)(N-2)(N-3)} \frac{1}{n^3}$$

$$\text{and } C_{rs} = \frac{1}{N} \sum_{i=1}^N \frac{(P_i - \bar{P})^r (Y_i - \bar{Y})^s}{\bar{P}^r \bar{Y}^s}$$

Proof of these lemma are straight forward by using SRSWOR (see Sukhatme and Sukhatme (1970)).

1. First Order Biases and Mean Squared Errors

The expressions for the biases of the estimators t_1, t_2, t_3 and t_4 are, respectively written as

$$\text{Bias}(t_1) = \bar{Y} \left[\frac{1}{2} \alpha L_1 C_{20} - \alpha L_1 C_{11} \right] \tag{4.1}$$

$$\text{Bias}(t_2) = \bar{Y} \left[\frac{g(g+1)}{2} L_1 C_{20} - g\beta L_1 C_{11} \right] \tag{4.2}$$

$$\text{Bias}(t_3) = \bar{Y} \left[-\frac{w(w-1)}{2} L_1 C_{20} - w L_1 C_{11} \right] \tag{4.3}$$

$$\text{Bias}(t_4) = \bar{Y} \left[-\frac{k(k-1)}{2} L_1 C_{20} - k L_1 C_{11} \right] \tag{4.4}$$

where, $k = \frac{(\delta + 2\lambda)}{2}$.

The expressions for the MSE's of the estimators t_1, t_2, t_3 and t_4 are , respectively, given by

$$MSE(t_1) = \bar{Y}^2 \left[L_1 C_{02} + \alpha^2 L_1 C_{20} - 2\alpha L_1 C_{11} \right] \quad (4.5)$$

$$MSE(t_2) = \bar{Y}^2 \left[L_1 C_{02} + g^2 \beta^2 L_1 C_{20} - 2g\beta L_1 C_{11} \right] \quad (4.6)$$

$$MSE(t_3) = \bar{Y}^2 \left[L_1 C_{02} + w^2 L_1 C_{20} - 2w L_1 C_{11} \right] \quad (4.7)$$

$$MSE(t_4) = \bar{Y}^2 \left[L_1 C_{02} + k^2 L_1 C_{20} - 2k L_1 C_{11} \right] \quad (4.8)$$

The MSE's of the estimators t_1, t_2, t_3 and t_4 under optimum conditions are equal to the MSE of the regression estimator when we consider the terms up to first order of approximations. In search of the optimum estimator, we have extended this study to second order of approximation.

1. Second Order Biases and Mean Squared Errors

Expressing estimator t_1 in terms of e 's ($i=0,1$), we get

$$t_1 = \bar{Y} (1 + c_0) \left\{ (1 - \alpha) + \alpha (1 + c_1)^{-1} \right\}$$

or

$$t_1 - \bar{Y} = \bar{Y} \left\{ c_0 + \frac{c_1}{2} + \frac{\alpha}{2} c_1^2 - \alpha c_0 c_1 + \alpha c_0 c_1^2 - \frac{\alpha}{6} c^3 - \frac{\alpha}{6} c_0 c_1^3 + \frac{\alpha}{24} c^4 \right\} \quad (5.1)$$

Taking expectations, we get the bias of the estimator t_1 up to the second order of approximation

as

$$\begin{aligned} \text{Bias}_2(t_1) = \bar{Y} \left[\frac{\alpha}{2} L_1 C_{20} - \alpha L_1 C_{11} - \frac{\alpha}{6} L_2 C_{30} + \alpha L_2 C_{21} - \frac{\alpha}{6} (L_3 C_{31} + 3L_4 C_{20} C_{11}) \right. \\ \left. + \frac{\alpha}{24} (L_3 C_{40} + 3L_4 C_{20}^2) \right] \quad (5.2) \end{aligned}$$

Similarly, we get the expressions for the biases of the estimator's $t_2, t_3,$ and t_4 up to second order of approximation as follows

$$\text{Bias}_2(t_2) = \bar{Y} \left[\frac{g(g+1)}{2} \beta^2 L_1 C_{20} - g\beta L_1 C_{11} - \frac{g(g+1)}{2} \beta^2 L_2 C_{21} - \frac{g(g+1)(g+2)}{6} \beta^3 L_2 C_{30} \right]$$

$$\begin{aligned}
 & - \frac{g(g+1)(g+2)}{6} \beta^3 (L_3 C_{31} + 3L_4 C_{20} C_{11}) \\
 & + \frac{g(g+1)(g+2)(g+3)}{24} \beta^4 (L_3 C_{40} + 3L_4 C_{20}^2) \Big] \quad (5.3)
 \end{aligned}$$

$$\begin{aligned}
 \text{Bias}_2(t_3) = \bar{Y} \Big[& \frac{w(w-1)}{2} L_1 C_{20} - wL_1 C_{11} - \frac{w(w-1)}{2} L_2 C_{21} - \frac{w(w-1)(w-2)}{6} L_2 C_{30} \\
 & - \frac{w(w-1)(w-2)}{6} (L_3 C_{31} + 3L_4 C_{20} C_{11}) \\
 & - \frac{w(w-1)(w-2)(w-3)}{24} (L_3 C_{40} + 3L_4 C_{20}^2) \Big] \quad (5.4)
 \end{aligned}$$

$$\begin{aligned}
 \text{Bias}_2(t_4) = \bar{Y} \Big[& - \frac{k(k-1)}{2} L_1 C_{20} - kL_1 C_{11} - \frac{k(k-1)}{2} L_2 C_{21} - ML_2 C_{30} - M(L_3 C_{31} + 3L_4 C_{20} C_{11}) \\
 & - N(L_3 C_{40} + 3L_4 C_{20}^2) \Big] \quad (5.5)
 \end{aligned}$$

where, $M = \frac{1}{2} \left\{ \frac{(\delta^3 - 6\delta^2)}{24} + \frac{(\alpha(\delta^2 - 2\delta))}{4} + \frac{\lambda(\lambda-1)}{2} \delta + \frac{\lambda(\lambda-1)(\lambda-2)}{3} \right\}$ and

$$k = \frac{(\delta + 2\lambda)}{2}$$

$N =$

$$\frac{1}{8} \left\{ \frac{(\delta^4 - 12\delta^3 + 12\delta^2)}{48} + \frac{(\alpha(\delta^3 - 6\delta))}{6} + \frac{\lambda(\lambda-1)}{2} (\delta^2 - 2\delta) + \frac{\lambda(\lambda-1)(\lambda-2)(\lambda-3)}{3} \right\}$$

Following are the expressions of the MSE's of the estimator's t_1 , t_2 , t_3 and t_4 respectively, up to second order of approximation

$$\begin{aligned}
 \text{MSE}_2(t_1) = \bar{Y}^2 \Big[& L_1 C_{02} + \alpha^2 L_1 C_{20} - 2\alpha L_1 C_{11} - \alpha^2 L_2 C_{30} + (2\alpha^2 + \alpha) L_2 C_{21} \\
 & - 2\alpha^2 (L_3 C_{31} + 3L_4 C_{20} C_{11}) \\
 & + \alpha(\alpha+1) (L_3 C_{22} + 3L_4 (C_{20} C_{02} + C_{11}^2)) - \frac{5}{24} \alpha^2 (L_3 C_{40} + 3L_4 C_{20}^2) \Big] \quad (5.6)
 \end{aligned}$$

$$\begin{aligned} \text{MSE}_2(t_2) = & \bar{Y}^2 \left[L_1 C_{02} + g^2 \beta^2 L_1 C_{20} - 2\beta g L_1 C_{11} - \beta^3 g^2 (g+1) L_2 C_{30} + g(3g+1) \beta^2 L_2 C_{21} \right. \\ & \left. - 2\beta g L_2 C_{12} - \left\{ \frac{7g^3 + 9g^2 + 2g}{3} \right\} \beta^3 (L_3 C_{31} + 3L_4 C_{20} C_{11}) \right. \\ & \left. + g(2g+1) \beta^2 (L_3 C_{22} + 3L_4 (C_{20} C_{02} + C_{11}^2)) \right. \\ & \left. + \left\{ \frac{2g^3 + 9g^2 + 10g + 3}{6} \right\} \beta^4 (L_3 C_{40} + 3L_4 C_{20}^2) \right] \end{aligned} \quad (5.7)$$

$$\begin{aligned} \text{MSE}_2(t_3) = & \bar{Y}^2 \left[L_1 C_{02} + w^2 L_1 C_{20} - 2w L_1 C_{11} - w^2 (w-1) L_2 C_{30} + w(w+1) L_2 C_{21} - 2w L_2 C_{12} \right. \\ & \left. + \left\{ \frac{5w^3 - 3w^2 - 2w}{3} \right\} (L_3 C_{31} + 3L_4 C_{20} C_{11}) \right. \\ & \left. + w (L_3 C_{22} + 3L_4 (C_{20} C_{02} + C_{11}^2)) + \left\{ \frac{7w^4 - 18w^3 + 11w^2}{24} \right\} (L_3 C_{40} + 3L_4 C_{20}^2) \right] \end{aligned} \quad (5.8)$$

$$\begin{aligned} \text{MSE}_2(t_4) = & \bar{Y}^2 \left[L_1 C_{02} + k^2 L_1 C_{20} - 2k L_1 C_{11} + k L_2 C_{21} - 2k L_2 C_{12} + k^2 (k-1) L_2 C_{30} \right. \\ & \left. + 2k^2 (k-1) (L_3 C_{31} + 3L_4 C_{20} C_{11}) + k (L_3 C_{22} + 3L_4 (C_{20} C_{02} + C_{11}^2)) \right. \\ & \left. + \frac{(k^2 - k)^2}{4} (L_3 C_{40} + 3L_4 C_{20}^2) \right] \end{aligned} \quad (5.9)$$

where, $k = \frac{(\delta + 2\lambda)}{2}$.

The optimum value of w for the constant involved in the estimator t_3 , we get by minimizing $\text{MSE}_2(t_3)$. But theoretically the determination of the optimum value of w is very difficult, so we have calculated the optimum value by using numerical techniques. Similarly, the optimum value of k which minimizes the MSE of the estimator t_4 is obtained by using numerical techniques.

1. Numerical Illustration

The various result obtained in the pervious sections are now examined with the help of the following data set:

Source of the Data

The data for the empirical analysis is taken from Sukhatme and Sukhatme (1970), p.256

Y = number of villages in the circles and

ϕ = A circle consisting more than five villages

$N=89$, $\bar{Y} = 3.36$, $P = 0.1236$, $\rho_{pb} = 0.766$, $C_y = 0.604$, $C_x = 2.19$.

Table 6.1: Biases and MSE's of estimators

Estimators	Bias		MSE	
	First order	Second order	First order	Second order
t_1	23.385388	24.42412947	17597.0515	23161.50715
t_2	-9.11939E-09	-0.84723967	17597.0515	17653.75783
t_3	18.30588379	26.44381147	17597.0515	19089.85861
t_4	18.30588379	55.4734888	17597.0515	18104.07826

In the Table 6.1 the biases and MSE's of the estimator's t_1 , t_2 , t_3 and t_4 are written under first order and second order of approximations. For all the estimators t_1 , t_2 , t_3 and t_4 it is observed that the value of the biases are increasing. For all estimators MSE's up to the first order of approximation under optimum conditions are equal, which encourage us to study the properties of the estimators up to the second order of approximation. On the basis of study up to the second order of approximation we conclude that estimator t_2 is best followed by t_4 , and t_3 among the estimators considered here for the given data set.

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